

# Income Tax: Enforcement and Compliance

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Lecture 1

# Income Tax I

Let

- $y$  denote the income level of an individual
- $e$  denote the income evaded/hidden from tax authority
- $y - e$  denote the income reported for tax purpose
- $t$  the tax rate
- $\pi$  probability that tax authority will detect and fine the evasion
- $F(e, t)$  fine in case of detection;  $F(0) = 0$ ,  $F'(e) > 0$
- Fine is paid over and above the tax on hidden income - you should also consider the case when fine is on hidden income.
- There is only one period and all of disposable income is consumed within the period

# Tax evasion and payoff I

Let

- Fine be imposed on tax evaded,  $et$ ,
- $F(e, t) = f(e)et$

Consumption levels:

Case 1: No evasion :  $c_0 = y(1 - t)$

Case 2 : When evasion goes undetected (with probability  $(1 - \pi)$  ) :  
 $\bar{c} = y - (y - e)t = y(1 - t) + et$

Case 3 : When Evasion is detected (with probability  $(\pi)$ ):  
 $\underline{c} = y - (y - e)t - (1 + f(e))et = y(1 - t) - f(e)et$

Hence, the rate of return on *tax evaded*,  $et$ , given by

$$\begin{bmatrix} -f(e) & \text{with } \pi \\ 1 & \text{with } 1 - \pi \end{bmatrix}$$

# Risk-neutral taxpayers I

Assume

- tax payers to be risk-neutral

Tax-payer's Expected Utility maximization problem is given as:

$$\max_e \{ \pi u(\underline{c}) + (1 - \pi)u(\bar{c}) \},$$

$$\max_e \{ \pi(y(1 - t) - f(e)et) + (1 - \pi)(y(1 - t) + et) \},$$

probability  $\pi$  is exogenously given. So the FOC is given by

$$\pi[-f(e).t - t.e.f'(e)] + (1 - \pi).t = 0 \quad (1)$$

If  $f'(e) = 0$ , then there will be a corner solution - either no evasion or full evasion. When  $f'(e) > 0$ , then evasion level is

$$e^*(t, \pi, y) = \frac{(1 - \pi) - \pi f(e)}{\pi f'(e)}$$

# Risk-aversion and Compliance: Illustration I

Assume

- tax payers to be risk-averse
- to get tax evasion assume:  $1 - \pi(1 + f(e = 0)) > 0$
- Linear Fine Function:  $F(et) = fet$
- Utility function:  $u(c) = \sqrt{c}$

$$EU = \pi[\sqrt{(1-t)y - fet}] + (1-\pi)[\sqrt{(1-t)y + et}]$$

FOC w.r.t.  $e$  is given by

$$\phi(e, t, \pi, y) = -\frac{f\pi}{\sqrt{c}} + (1-\pi)\frac{1}{\sqrt{c}} = 0$$

Thus  $e^*$  solves:

$$\frac{1-\pi}{\pi} = \frac{f\sqrt{c}}{\sqrt{c}} = \frac{f\sqrt{(1-t)y + et}}{\sqrt{(1-t)y - fet}}$$

## Risk-aversion and Compliance: Illustration II

### Proposition

$\frac{de^*}{d\pi} < 0$ ,  $\frac{de^*}{df} < 0$ . What about  $\frac{de^*}{dt}$  ?

For given  $t$ ,  $\pi$  and  $y$ , the above FOC can be written as:

$$\phi(\mathbf{e}, t, \pi, y) = 0$$

Let  $\mathbf{e}^*(t, \pi, y)$  solve the FOC. Note: For  $\tau = t, \pi, y$ ,

$$\frac{\partial \phi}{\partial \tau} + \frac{\partial \phi}{\partial \mathbf{e}^*} \frac{\partial \mathbf{e}^*}{\partial \tau} = 0 \quad (2)$$

So

$$\frac{\partial \mathbf{e}^*}{\partial \tau} = - \frac{\frac{\partial \phi}{\partial \tau}}{\frac{\partial \phi}{\partial \mathbf{e}^*}}$$

Here we have  $\frac{\partial \phi}{\partial \mathbf{e}^*} < 0$ . Moreover,

## Risk-aversion and Compliance: Illustration III

$\frac{\partial \phi}{\partial \pi} < 0$  and  $\frac{\partial \phi}{\partial f} < 0$  and  $\frac{\partial \phi}{\partial t} < 0$  and  $\frac{\partial \phi}{\partial y} > 0$  always.

So, we get:

$$\frac{\partial e^*}{\partial \pi} < 0 \text{ and } \frac{\partial e^*}{\partial f} < 0.$$

Similarly, we get

$$\frac{\partial e^*}{\partial y} > 0 \text{ and } \frac{\partial e^*}{\partial t} < 0$$

Note : We can get the same signs by directly differentiating  $e^*$  with respect to different parameters.

# Risk-aversion and (Non)Compliance Decision I

In general Tax-payer's Expected Utility maximization problem is given as:

$$\max_e \{ \pi u(\underline{c}) + (1 - \pi)u(\bar{c}) \},$$

$$\max_e \{ \pi u(y(1 - t) - f(e)et) + (1 - \pi)u(y(1 - t) + et) \},$$

probability  $\pi$  is exogenously given. So the FOC is given by

$$\pi \cdot u_{\underline{c}}(\underline{c})[-f(e) \cdot t - t \cdot e \cdot f'(e)] + (1 - \pi) \cdot t \cdot u_{\bar{c}}(\bar{c}) = 0 \quad (3)$$

$$e^*(t, \pi, y) = \frac{(1 - \pi)u_{\bar{c}}(\bar{c}) - \pi \cdot u_{\underline{c}}f(e)}{\pi \cdot u_{\underline{c}}(\underline{c}) \cdot f'(e)}$$

Let

$$\phi(e, t, \pi, y) \equiv \pi \cdot u_{\underline{c}}(\underline{c})[-f(e) \cdot t - t \cdot e \cdot f'(e)] + (1 - \pi) \cdot t \cdot u_{\bar{c}}(\bar{c})$$

So, for given  $t, \pi$  and  $y$ , FOC (1) can be written as:

$$\phi(e, t, \pi, y) = 0$$



## Risk-aversion and (Non)Compliance Decision II

Let  $e^*(t, \pi, y)$  solve the FOC. Note:

$$\frac{\partial \phi}{\partial \pi} + \frac{\partial \phi}{\partial e^*} \frac{\partial e^*}{\partial \pi} = 0 \quad (4)$$

So

$$\frac{\partial e^*}{\partial \pi} = - \frac{\frac{\partial \phi}{\partial \pi}}{\frac{\partial \phi}{\partial e^*}}$$

$$\begin{aligned} \frac{\partial \phi}{\partial e} &= -\pi \cdot \underline{u}_{\underline{c}}(\underline{c}) [2f'(e) + e \cdot f''(e)] - [f(e) + e \cdot f'(e)]^2 \cdot \underline{u}_{\underline{c}\underline{c}}(\underline{c}) \\ &+ (1 - \pi) \cdot \underline{u}_{\bar{c}\bar{c}}(\bar{c}) \end{aligned}$$

$$\frac{\partial \phi}{\partial t} = \pi [f(e) + e \cdot f'(e)] \cdot \underline{u}_{\underline{c}\underline{c}}(\underline{c}) (f(e) \cdot e + y) - (1 - \pi) \cdot \underline{u}_{\bar{c}\bar{c}}(\bar{c}) (y - e)$$

$$\frac{\partial \phi}{\partial \pi} = -\underline{u}_{\underline{c}}(\underline{c}) \cdot [f(e) + e \cdot f'(e)] - \underline{u}_{\bar{c}}(\bar{c})$$

$$\frac{\partial \phi}{\partial y} = (1 - t) [-\pi (f(e) + e f'(e)) \cdot \underline{u}_{\underline{c}\underline{c}}(\underline{c}) + (1 - \pi) \underline{u}_{\bar{c}\bar{c}}(\bar{c})]$$

## Risk-aversion and (Non)Compliance Decision III

$$\frac{\partial \phi}{\partial e} < 0 \text{ if } f''(e) \geq 0, \text{ \& } \frac{\partial \phi}{\partial \pi} < 0 \text{ \& } \frac{\partial \phi}{\partial y} > 0$$

Note:  $\frac{\partial \phi}{\partial t} < 0$  if

$$\pi[f(e) + e.f'(e)].u_{\underline{c}\underline{c}}(\underline{c})(f(e).e + y) < (1 - \pi).u_{\bar{c}\bar{c}}(\bar{c})(y - e)$$

We know that  $(y + f(e)e) > (y - e)$  and under Decreasing Absolute Risk Aversion

$$-\frac{u_{\underline{c}\underline{c}}(\underline{c})}{u_{\underline{c}}(\underline{c})} > -\frac{u_{\bar{c}\bar{c}}(\bar{c})}{u_{\bar{c}}(\bar{c})}.$$

That is,

$$\frac{(f(e).e + y)u_{\underline{c}\underline{c}}(\underline{c})}{u_{\underline{c}}(\underline{c})} < \frac{(y - e)u_{\bar{c}\bar{c}}(\bar{c})}{u_{\bar{c}}(\bar{c})}$$

## Risk-aversion and (Non)Compliance Decision IV

From FOC we have

$$\pi \cdot u_{\underline{c}}(\underline{c})[-f(e) \cdot t - t \cdot e \cdot f'(e)] + (1 - \pi) \cdot t \cdot u_{\bar{c}}(\bar{c}) = 0, \text{ i.e.,}$$

$$\frac{\pi[f(e) + e \cdot f'(e)]}{1 - \pi} = \frac{u_{\bar{c}}(\bar{c})}{u_{\underline{c}}(\underline{c})}$$

Therefore the condition for  $\frac{\partial \phi}{\partial t} < 0$  will always hold.

From (2)

$$\frac{\partial e^*}{\partial \pi} = -\frac{\frac{\partial \phi}{\partial \pi}}{\frac{\partial \phi}{\partial e}} < 0$$

That is, Ceteris paribus, the level of evaded income  $e^*$  decreases as probability of detection ( $\pi$ ) increases.

## Risk-aversion and (Non)Compliance Decision V

Similarly, the effect of tax rate on the evaded income is negative.

$$\frac{\partial e^*}{\partial t} = -\frac{\frac{\partial \phi}{\partial t}}{\frac{\partial \phi}{\partial e}} < 0$$

Ceteris paribus, the effect of change in actual income on evaded income .

$$\frac{\partial e^*}{\partial y} = -\frac{\frac{\partial \phi}{\partial y}}{\frac{\partial \phi}{\partial e}} > 0$$

# Quality of Governance and Compliance: Example I

- Tax revenue is given by  $T = (y, e, t, \pi)$
- $\lambda$  fraction of the tax collected is spent of public good - the rest is misappropriated by the government
- Public good production function is such that

$$g = g(\lambda, T) = g(\lambda, y, e, t, \pi); \quad g'(e) < 0$$

Example:

- Constant Fine  $F() = fet$
- $g = \lambda(y - e)t$
- Utility function:  $u(c, g) = \sqrt{c} + \sqrt{g}$

## Quality of Governance and Compliance: Example II

$$EU = \pi[\sqrt{(1-t)y - fet} + \sqrt{g}] + (1-\pi)[\sqrt{(1-t)y + et} + \sqrt{g}]$$

FOC is given by

$$(1-\pi)[u_{\bar{c}}(\bar{c}, g)t + u_g(\bar{c}, g)\lambda g'(e)] \\ + \pi[u_{\underline{c}}(\underline{c}, g)[-ft] + u_g(\underline{c}, g)\lambda g'(e)] = 0$$

$$\phi(e, t, \pi, y) = -\frac{f\pi}{\sqrt{\underline{c}}} + (1-\pi)\frac{1}{\sqrt{\bar{c}}} - \frac{\lambda t}{2\sqrt{g}} = 0$$

# Quality of Governance and Compliance: Example III

Thus  $e^*$  solves:

$$\frac{1 - \pi}{\pi} = \frac{f\sqrt{c}}{\sqrt{c}} + \frac{\lambda\sqrt{c}}{\pi\sqrt{g}} = \frac{f\sqrt{(1-t)y + et}}{\sqrt{(1-t)y - fet}} + \frac{\lambda\sqrt{c}}{\pi\sqrt{g}}$$

Now ,

$$e^* > e^{*P}$$

Question

$$\frac{de^{*P}}{d\pi}, \frac{de^{*P}}{df}, \frac{de^{*P}}{dt}, \text{ etc ?}$$